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 $x(t)$ is $dt \cdot t \cdot dx$ (is Because $- = - = k \cdot k \cdot t \cdot g$
 $2 (d, dt \cdot t \cdot dx) (=3g(t)-3g(t-1)$ or $dt \cdot t \cdot dx$
 $(=3g(t)-3g(t+1)$ 1.15.Consider a system
S with input $x[n]$ and output $y[n]$.This

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Solution 1.4 (a) This can be considered the result of delaying the input $x(t)$ by 2, then feeding the result to a system with impulse response $h_0(t) = e^{-t}u(t)$, so $h(t) = e^{-(t-2)}u(t-2)$. The answer can be checked by setting $x(t) = (t)$; the integral

then evaluates to $e^{-(t-2)}$ for $t \geq 2$, and to 0 otherwise.

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