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Discrete control #2: Discretize!

Going from continuous to discrete domain

State Space representation of Discrete Time Systems

3 | Digital Control

Digital control 1: Overview

Introduction to State Variable Analysis of Discrete Time Control Systems.

Why Z transforms? For discrete time control systems DCS-unit2

LEC-1 Hardware Demo of a Digital PID Controller

Introduction, Part I: Differences between analogue and digital controllers (subtitles)

2/3/2014 Discrete-Time Systems — Impulse Sampler

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Discrete-Time Systems — Z-transform

Zero-Order Hold (Lecture 5 — Part II)

State space feedback — optimal control

Response of a first order system to an impulse,

3/4/2014 State Space, Part 4: What is LQR control?

ECE320 Lecture10-1c: Discrete-Time Systems

- Transfer Function Control

Intro to Control - 5.1 Linearization

Basics An explanation of the Z transform part 1

State Variable Analysis in Discrete Time Domain

State Space Analysis — Control Systems

Discrete-Time-Systems - Pulse Transfer Functions of a Digital Control System (Lecture 6 - Part II)

Digital control 10: Continuous-time models of discrete-time

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8: Stability of discrete-time systems *Digital control 9: Overview of discrete-time systems and signals*

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